

Operations research: Mathematics and algorithmics for solving decision-making problems

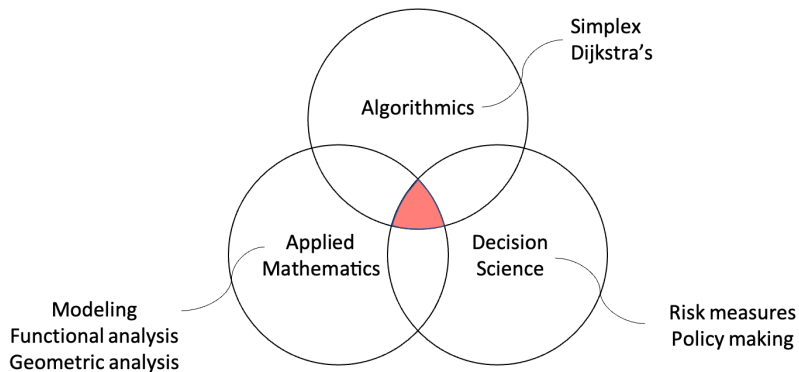
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Centre Inria de l'Université de Bordeaux
Equipe : EDGE

Midis Math
28/11/2023

Operations research (OR)

- Operations research and optimization are at the intersection of multiple disciplines.



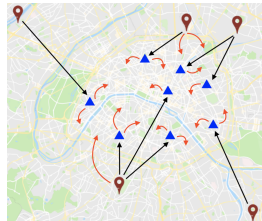
Operations research (OR)

- ▶ OR solves optimization problems that decision-makers (managers, politicians, engineers, etc.) encounter.
- ▶ Problems are typically expressed in terms of decisions, costs and constraints.
- ▶ Tools coming from mathematics, informatics, economics and industrial engineering are often used in their solution.
- ▶ The end result is a decision-making tool.

$$\min_{x \in X} f(x)$$

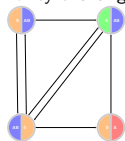
Some examples

- ▶ Route optimization
- ▶ Planning and scheduling
- ▶ Network design (telecommunications, distribution, electricity, etc.)
- ▶ Supply chain management



Some projects from our team¹

Kidney exchange



Maintenance planning



Retail network design



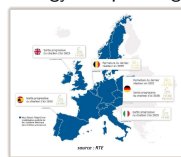
Phytosanitary treatments



Maritime transportation



Energy mix planning



¹Team EDGE-Centre Inria de l'Université de Bordeaux

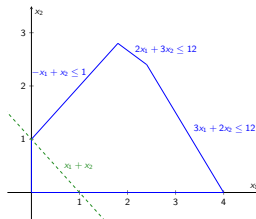
Classical tools of operations research²

- ▶ **Mathematical programming**
 - ▶ Linear programming (LP/PL)
 - ▶ Mixed-integer linear programming (MILP/PLNE)
 - ▶ ..
- ▶ **Graph theory and algorithms**
- ▶ Constraint programming (CP/PPC)
- ▶ Convex analysis
- ▶ Approximation algorithms
- ▶ Heuristics, metaheuristics
- ▶ Queueing theory, simulation, statistics
- ▶ ...

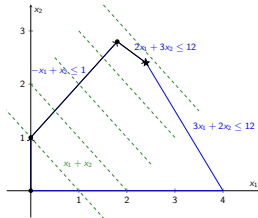
²Most topics are covered in the master MAS-ROAD

Mathematical programming: Linear programming

$$\begin{aligned} \min_{\mathbf{x} \in \mathbb{R}_+^n} \quad & \mathbf{c}^\top \mathbf{x} \\ \text{s.t.} \quad & \mathbf{Ax} \leq \mathbf{b} \end{aligned}$$



- ▶ Well-known algorithms: Simplex, ellipsoid, interior point, etc.
- ▶ Solvers: CPLEX, Gurobi, Clp, HiGHS, Excel-Solver etc.

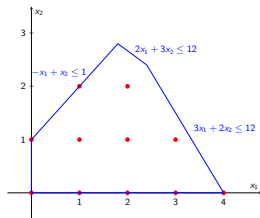


$$\begin{aligned} z &= \mathbf{c}_B^\top \mathbf{A}_B^{-1} \mathbf{b} + \left(\mathbf{c}_N - \mathbf{c}_B^\top \mathbf{A}_B^{-1} \mathbf{A}_N \right)^\top \mathbf{x}_N \\ \mathbf{x}_B &= \mathbf{A}_B^{-1} \mathbf{b} - \mathbf{A}_B^{-1} \mathbf{A}_N \mathbf{x}_N \end{aligned}$$

Mathematical programming: Mixed-integer programming

$$\begin{array}{ll} \min & \mathbf{c}^\top \mathbf{x} \\ \text{s.t.} & \mathbf{Ax} \leq \mathbf{b} \end{array}$$

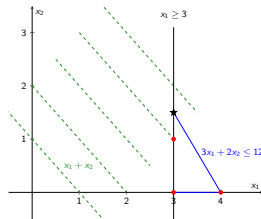
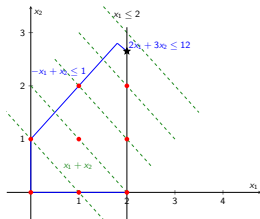
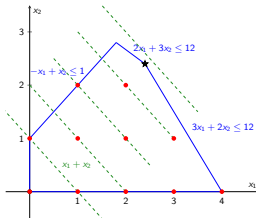
$\mathbf{x} \in \mathbb{Z}_+^{n_1} \times \mathbb{R}_+^{n_2}$



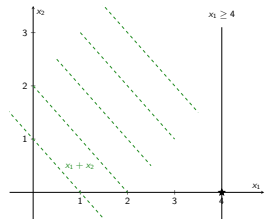
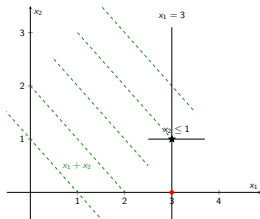
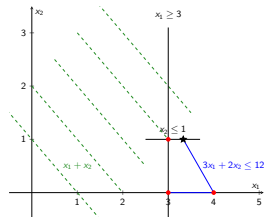
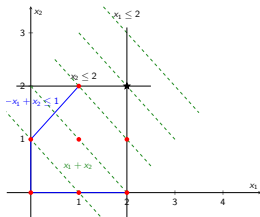
- ▶ Integer/binary decisions that cannot be rounded from fractions:
 - ▶ Do we open facility i or not?
 - ▶ How many trucks do we need to send to client j from facility i ?
 - ▶ If facility i is not open then it cannot be used to satisfy demand.
- ▶ Well-known algorithms: Branch & Bound, Branch & Cut etc.
- ▶ Solvers: CPLEX, Gurobi, HiGHS, GLPK etc.

Mathematical programming: Mixed-integer programming

- Branch & Bound: Solve relaxations and successively partition the feasible region



Mathematical programming: Mixed-integer programming



Difficulty of mixed-integer programming problems³

- ▶ Mixed-integer programming problems are NP-Complete in the general case.
- ▶ In practice, considerable progress has been made since the beginning.

A classical problem: Traveling salesman

- ▶ Find the shortest cycle passing through N cities given the pairwise distances.
- ▶ In theory finding the best cycle requires testing $N!$ possibilities.
 - ▶ For 10 cities ($N=10$) : < 1 milliseconds
 - ▶ For 30 cities ($N=30$) : 35000 billion years



³Source : <http://www.math.uwaterloo.ca/tsp/>

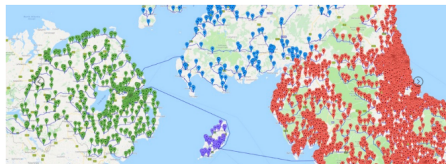
Difficulty of mixed-integer programming problems³

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- ▶ In practice, considerable progress has been made since the beginning.

1954	1977	1987	1994	1998	2001	2004
N = 49	N = 120	N=2392	N=7397	N=13509	N=15112	N=24978

UK49687

Shortest possible tour to nearly every pub in the United Kingdom.



Optimal 49,687-stop pub crawl. [Click.](#)

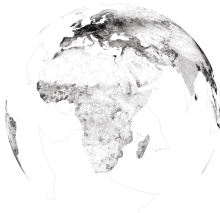
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³Source : <http://www.math.uwaterloo.ca/tsp/>

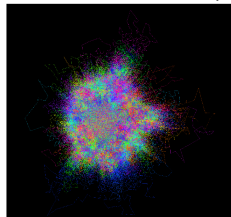
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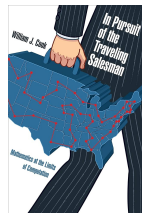
1.9 millions cities to 0.0473% optimality



1 331 906 450 stars to 0.37% optimality

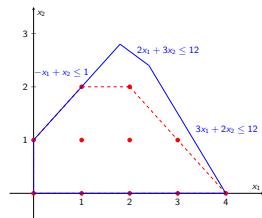
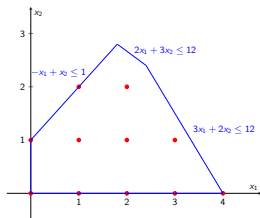


- ▶ Powerful heuristics coupled with branch & cut
- ▶ Many results dedicated to the problem
- ▶ Months of computation in parallel processing



³Source : <http://www.math.uwaterloo.ca/tsp/>

Advanced techniques in mixed-integer programming

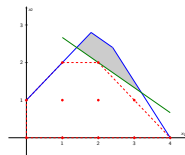
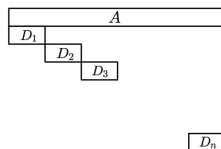
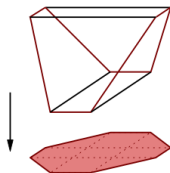
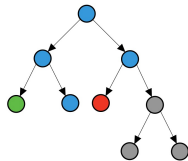


Implicit enumeration

Extended formulations

Decomposition algorithms

Geometric analysis



What is the Kidney Exchange Problem (KEP)?

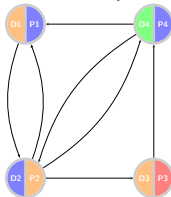
- ▶ Chronic kidney disease is a serious health condition threatening the lives of many in our society.
- ▶ It is the 11th most common cause of death in the world.
- ▶ There are two common treatments for this disease : dialysis and kidney transplant.
- ▶ Dialysis is easily available but requires weakly visits to the hospital and degrades the quality of life of the patient.
- ▶ Kidney transplants, once successfully performed may give the patients the chance for a healthy life.
- ▶ Finding a willing and compatible donor can be very difficult.



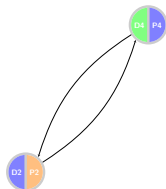
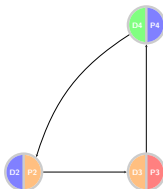
What is the Kidney Exchange Problem (KEP)?

- ▶ Given
 - ▶ A list of incompatible patient-donor pairs
 - ▶ The compatibility information between donors and patients of different pairs
 - ▶ A limit K on the size of cycles
- ▶ Find a set of exchange cycles such that
 - ▶ Each cycle has size $\leq K$
 - ▶ Each patient-donor pair is involved in at most one cycle
 - ▶ A maximum number of transplants is performed

Instance with 4 pairs, $K=3$



Possible solutions



This problem is known to be NP-Complete for $K \in [3, \infty)$.

A possible mathematical formulation of the problem

► Data

- \mathcal{P} : set of patient-donor pairs indexed $i = 1, \dots, |\mathcal{P}|$
- $(i, j) \in \mathcal{A}$: compatibility information between donors and patients of different pairs
- K : cycle size limit

► Variables

- $x_{ij} \in \{0, 1\}$: 1 if a transplant between donor of pair i and patient of pair j is to be performed, 0 otherwise

$$\begin{aligned}
 \max \quad & \sum_{(i,j) \in \mathcal{A}} x_{ij} \\
 \text{s.t.} \quad & \sum_{j \in \delta^+(i)} x_{ij} = \sum_{j \in \delta^-(i)} x_{ji} & \forall i \in \mathcal{P} \\
 & \sum_{j \in \delta^+(i)} x_{ij} \leq 1 & \forall i \in \mathcal{P} \\
 & x \in \{0, 1\}^{|\mathcal{A}|}
 \end{aligned}$$

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 & \sum_{j \in \delta^+(i)} x_{ij} \leq 1 & \forall i \in \mathcal{P} \\
 & \sum_{(i,j) \in \text{Path}} x_{ij} \leq K - 1 & \forall \text{Path} \in \text{AllPaths}(K) \\
 & x \in \{0, 1\}^{|\mathcal{A}|}
 \end{aligned}$$

Another possible mathematical formulation

► Data

- \mathcal{P} : set of patient-donor pairs indexed $i = 1, \dots, |\mathcal{P}|$
- $(i, j) \in \mathcal{A}$: compatibility information between donors and patients of different pairs
- K : cycle size limit

► Additional data

- \mathcal{C}_K : set of cycles of size at most K
- $\mathcal{C}_K(i)$: set of cycles of size at most K containing pair i
- $|c|$ for $c \in \mathcal{C}_K$: number of pairs involved in cycle c

► Variables

- $x_c \in \{0, 1\}$: 1 if cycle $c \in \mathcal{C}_K$ is chosen as part of the solution, 0 otherwise

$$\begin{aligned}
 \max \quad & \sum_{c \in \mathcal{C}_K} |c| x_c \\
 \text{s.t.} \quad & \sum_{c \in \mathcal{C}_K(i)} x_c \leq 1 & \forall i \in \mathcal{P} \\
 & x \in \{0, 1\}^{|c|}
 \end{aligned}$$

Yet another possible mathematical formulation

► Data

- \mathcal{P} : set of patient-donor pairs indexed $i = 1, \dots, |\mathcal{P}|$
- $(i, j) \in \mathcal{A}$: compatibility information between donors and patients of different pairs
- K : cycle size limit

► Variables

- $x_{ij}^p \in \{0, 1\}$: 1 if a transplant between donor of pair i and patient of pair j is to be performed in a cycle starting from pair p , 0 otherwise

$$\begin{aligned}
 \max \quad & \sum_{p \in \mathcal{P}} \sum_{(i,j) \in \mathcal{A}} x_{ij}^p \\
 \text{s.t.} \quad & \sum_{j \in \delta^+(i)} x_{ij}^p = \sum_{j \in \delta^-(i)} x_{ji}^p \quad \forall p \in \mathcal{P}, \forall i \in \mathcal{P} \\
 & \sum_{(i,j) \in \mathcal{A}} x_{ij}^p \leq K \quad \forall p \in \mathcal{P} \\
 & \sum_{p \in \mathcal{P}} \sum_{j \in \delta^+(i)} x_{ij}^p \leq 1 \quad \forall i \in \mathcal{P} \\
 & x \in \{0, 1\}^{|\mathcal{A}| \times |\mathcal{P}|}
 \end{aligned}$$

$$\begin{aligned}
 \sum_{j \in \delta^+(i)} x_{ij}^1 &= \sum_{j \in \delta^-(i)} x_{ji}^1 \quad \forall i \in \mathcal{P} \\
 \sum_{(i,j) \in \mathcal{A}} x_{ij}^1 &\leq K \\
 \sum_{j \in \delta^+(i)} x_{ij}^2 &= \sum_{j \in \delta^-(i)} x_{ji}^2 \quad \forall i \in \mathcal{P} \\
 \sum_{(i,j) \in \mathcal{A}} x_{ij}^2 &\leq K \\
 &\dots \\
 \sum_{j \in \delta^+(i)} x_{ij}^{|\mathcal{P}|} &= \sum_{j \in \delta^-(i)} x_{ji}^{|\mathcal{P}|} \quad \forall i \in \mathcal{P} \\
 \sum_{(i,j) \in \mathcal{A}} x_{ij}^{|\mathcal{P}|} &\leq K \\
 \sum_{p \in \mathcal{P}} \sum_{j \in \delta^+(i)} x_{ij}^p &\leq 1 \quad \forall i \in \mathcal{P}
 \end{aligned}$$

And finally...

► Data

- \mathcal{P} : set of patient-donor pairs indexed $i = 1, \dots, |\mathcal{P}|$
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► Additional data

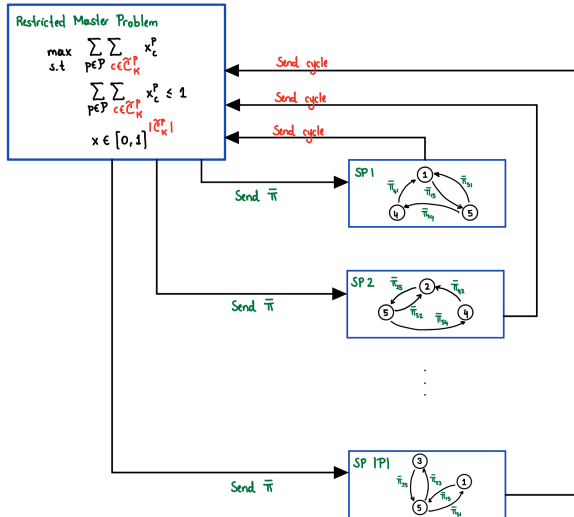
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- $\mathcal{C}_K^p(i)$: set of cycles of size at most K starting from pair p containing pair i
- $|c|$ for $c \in \mathcal{C}_K^p$: number of pairs involved in cycle c

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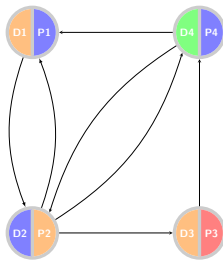
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 & x \in \{0, 1\}^{|\mathcal{C}_K^p|} & \forall p \in \mathcal{P}
 \end{aligned}$$

Column generation algorithm



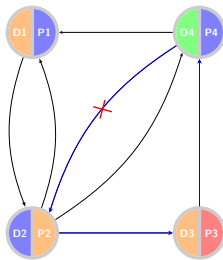
What about uncertainty?

- In reality the compatibility information is only known with certainty after performing costly tests.



What about uncertainty?

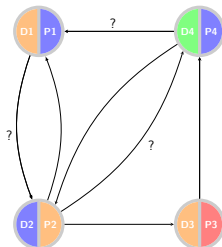
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- Constructed cycles can break after these tests are performed.

What about uncertainty?

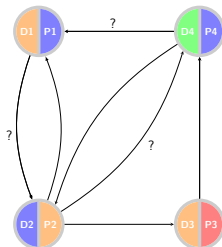
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- A better strategy is to test first and then construct a solution with the acquired compatibility information.

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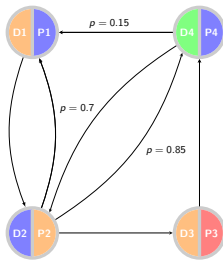
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- A better strategy is to test first and then construct a solution with the acquired compatibility information.
- Then a question arises as to what donor-patient pairs to test with a limited budget.

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- Constructed cycles can break after these tests are performed.
- A better strategy is to test first and then construct a solution with the acquired compatibility information.
- Then a question arises as to what donor-patient pairs to test with a limited budget.

Requires development of optimization under uncertainty approaches.

Conclusions

- ▶ OR is an interdisciplinary field that studies decision-making problems from a mathematical and algorithmic perspective.
- ▶ It develops tools to help decision makers.
- ▶ Significant algorithmic progress has been made in recent years.
- ▶ Further research is needed in order to extend classical results to more realistic contexts.

Questions?



*Thank you for your attention!
Any questions?*

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Appendix:
Optimisation under uncertainty

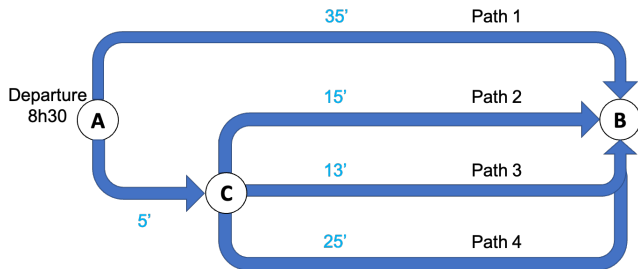
Presence of uncertainty

- ▶ New challenges:
 - ▶ Renewable energy production.
 - ▶ Resilient network design.
 - ▶ Healthcare/disaster management.
 - ▶ Circular economy.
 - ▶ Security and defense.



- ▶ Uncertainty:
 - ▶ Stochastic nature of systems.
 - ▶ Long duration of decision processes.
 - ▶ Difficulty of precise measurements.
 - ▶ Lack of historical information.
 - ▶ Presence of adversarial participants.

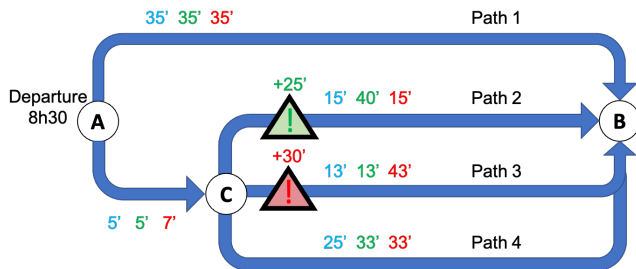
A practical example: Shortest path under uncertainty



Path 1	35'
Path 2	20'
Path 3	18'
Path 4	30'

- What is the shortest path from point A to point B?

A practical example: Shortest path under uncertainty

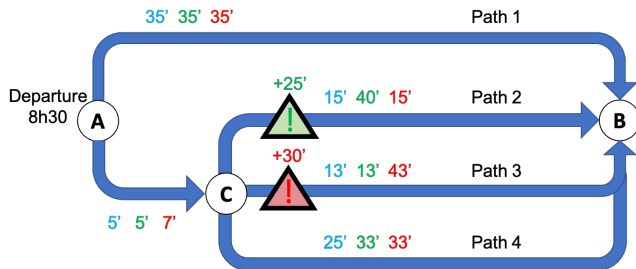


Scenario	Probability
1	0,5
2	0,25
3	0,25

- What is the shortest path from point A to point B?

Our first order of business is to characterize the uncertain data.

A practical example: Shortest path under uncertainty



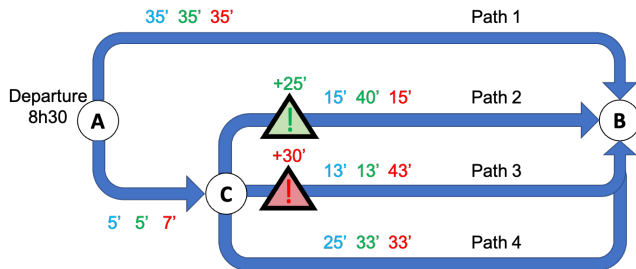
Scenario	Probability
1	0,5
2	0,25
3	0,25

Scenario	1	2	3
Path 1	35'	35'	35'
Path 2	20'	45'	22'
Path 3	18'	18'	50'
Path 4	30'	38'	40'

- What is the shortest path from point A to point B?

Second order of business is to characterize what constitutes a "good" solution.

A practical example: Shortest path under uncertainty



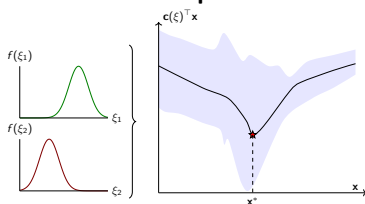
Scenario	Probability
1	0,5
2	0,25
3	0,25

Scenario	1	2	3	Esp	Max
Path 1	35'	35'	35'	35'	35'
Path 2	20'	45'	22'	26,75'	45'
Path 3	18'	18'	50'	26'	50'
Path 4	30'	38'	40'	34,5'	38'

In optimization under uncertainty the notion of a good solution depends on the risk preferences of the decision-maker.

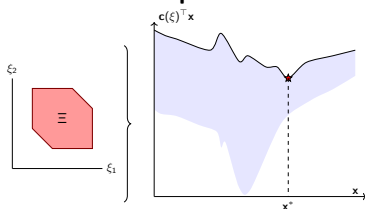
Optimization under uncertainty paradigms

Stochastic optimization



- Distribution \mathbb{P} is known.
- Consequences are observed repeatedly.
- Risk level is low or moderate.
- Example: Distribution network design.

Robust optimization



- Distribution is not known (or no distribution).
- Consequences are observed once.
- Risk level is high.
- Example: Disaster management.

Optimization under uncertainty paradigms

Stochastic optimization

$$\begin{aligned} \min_{\mathbf{x} \in X} \quad & \mathbb{E}_{\xi \in \Xi}^{\mathbb{P}} \left[\mathbf{c}(\xi)^{\top} \mathbf{x} \right] \\ \text{s.t.} \quad & \mathbf{Ax} \leq \mathbf{b} \end{aligned}$$

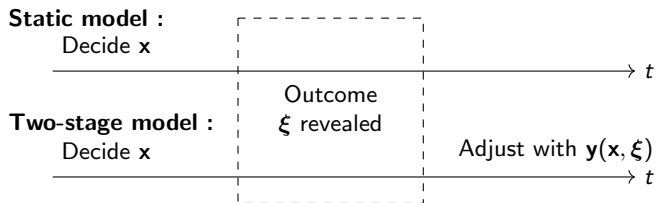
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Robust optimization

$$\begin{aligned} \min_{\mathbf{x} \in X} \quad & \max_{\xi \in \Xi} \left[\mathbf{c}(\xi)^{\top} \mathbf{x} \right] \\ \text{s.t.} \quad & \mathbf{Ax} \leq \mathbf{b} \end{aligned}$$

- ▶ Distribution is not known (or no distribution).
- ▶ Consequences are observed once.
- ▶ Risk level is high.
- ▶ Example: Disaster management.

Sequential decision-making under uncertainty



In optimization under uncertainty the timing of decisions is important.

The difficulty of solution can increase with the number of decision stages.